

# Tidal evolution

Tidal deformation  
Rotational  
deformation  
Tidal torques  
Orbit decay and spin  
down rates  
Tidal circularization  
Hot Jupiters

# Tidal and rotational deformations

- Give information on the interior of a body, so are of particular interest
- Tidal forces can also be a source of heat and cause orbital evolution

# Potentials of non-spherical bodies

- External to the planet the gravitational potential is zero

$$\nabla^2 \Phi = 0$$

- Separate in  $r, \phi, \theta$
- Can expand in spherical harmonics with general solution

$$\Phi(r, \phi, \mu) = \sum_n (A_n r^n + B_n r^{-(n+1)}) S_n(\mu, \phi)$$

- Given axisymmetry the solutions are only a function of  $\mu = \cos(\theta)$  and are

Legendre Polynomials, with

$$\begin{aligned} P_1(\mu) &= \mu \\ P_2(\mu) &= \frac{1}{2}(3\mu^2 - 1) \end{aligned}$$

# Potential External to a non-spherical body

- For a body with constant density  $\gamma$  body, mean radius  $C$  and that has an equatorial bulge

$$R(\theta) = C(1 + \epsilon_2 P_2(\cos(\theta)))$$

- Has exterior gravitational potential

$$\Phi(r, \theta) = -\frac{4}{3}\pi C^3 \gamma G \left( \frac{1}{r} + \frac{3}{5} \frac{C^2}{r^3} \epsilon_2 P_2(\cos \theta) \right)$$

- And internal potential

$$\Phi(r, \theta) = -\frac{4}{3}\pi C^3 \gamma G \left[ \frac{3C^2 - r^2}{2C^3} + \frac{3}{5} \frac{r^2}{C^3} \epsilon_2 P_2(\cos \theta) \right]$$

# Potential external to a non-spherical body

- Quadrupole component only

$$\Phi_2 \sim -\frac{GM R^2}{r^3} \epsilon_2 P_2(\cos \theta)$$

- Form useful for considered effect of rotation and tidal forces on shape and external potential

# Rotational deformation

- Can define an effective potential which includes a centripetal term

$$\Phi_{cf} = \frac{\Omega^2 r^2}{3} [P_2(\cos \theta) - 1] \quad \text{factor of 3 from definition of } P_2$$

- Flattening depends on ratio of centrifugal to gravitational acceleration

$$q = \frac{\Omega^2 R^3}{Gm_p}$$

- Exterior to body

$$\Phi(r, \theta) = -\frac{GM}{r} \left[ 1 - \sum_n J_n \left( \frac{R}{r} \right)^n P_n(\cos \theta) \right]$$

- Taking  $J_2$  term only and assuming isopotential surface

$$gh + J_2 \frac{Gm_p}{R} + \frac{\Omega^2 R^2}{3} = 0$$

$$f = \frac{3}{2} J_2 + \frac{q}{2}$$

rewrite this in terms of difference between pole and equatorial radius,  $f$  and flattening  $q$  parameter

# Rotational deformation

- It is also possible to relate  $J_2$  to moments of inertia

$$J_2 \approx \frac{C - A}{Ma^2}$$

- Where C,A are moments of inertia and **a** is a long axis of the body

# Rotational deformation

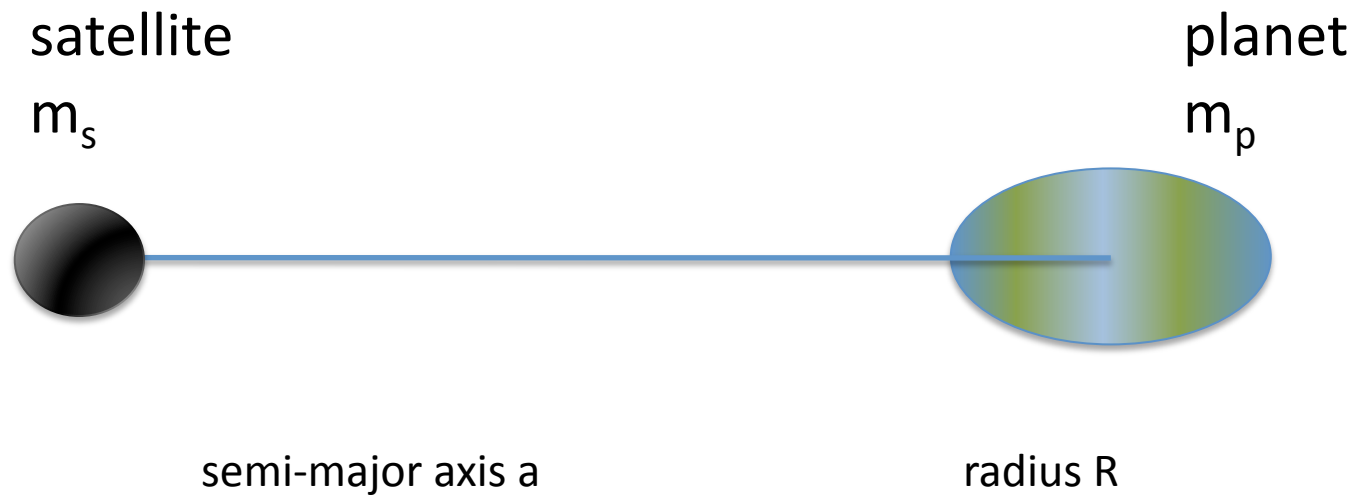
- Again assume surface is a zero potential equilibrium state
- Balance  $J_2$  term with centrifugal term to relate oblateness ( $f=\delta r/r$ ) to moments of inertia ( $J_2$ ) and rotation

$$f = \frac{3}{2}J_2 + \frac{q}{2}$$

- Observables from a distance: oblateness  $f$ , spin parameter,  $q$
- Resulting constraint on moments of inertia which gives information on the density distribution in the body
- $J_2$  can also be measured from a flyby or by observing precession of an orbit



# Tidal Deformation



# Tidal Deformation

- Tidal deformation by an external object
- In equilibrium body deforms into a shape along axis to perturber

$$R(\theta) = C(1 + \epsilon_2 P_2(\cos(\theta)))$$

- Surface is approximately an equipotential surface
- That of body due to itself must balance that from external tide.
- Tidal potential  $V_T$
- Body assumed to be in hydrostatic equilibrium
- Height  $x$  surface acceleration is balanced by external tidal perturbation

$$gh \sim V_T$$

$$h = \epsilon C$$

$C$  = mean radius

$$g = \frac{Gm_p}{C^2}$$

surface acceleration

# Tidal force due to an external body

- External body with mass  $m_s$ , and distance to planet of  $a$
- Via expansion of potential the tidal force from satellite onto planet is

$$\Phi(\psi) = -G \frac{m_s}{a^3} R_p^2 P_2(\cos \psi)$$

- Where  $\psi$  is defined as along satellite planet axis
- If we assume constant density then this can be equated to potential term of a bulging body to find  $\epsilon$  the size of the equatorial deformation from spherical
- More sophisticated can treat core and ocean separately each with own density and boundary and using the same expressions for interior and exterior potential

# Planet's potential

equipotential surface  $h(\psi)$  and acceleration  $g = \frac{GM_p}{R_p^2}$

$gh(\psi)$  acceleration times height above mean surface is balanced by tidal potential at the surface

$$= \frac{Gm_s}{a^3} R_p^2 P_2(\cos \psi)$$

for these to balance  $h(\psi)$  must be proportional to  $P_2(\cos \psi)$


$$h \sim R_p \frac{m_s}{M_p} \left( \frac{R_p}{a} \right)^3$$

The potential generated by the deformed planet, **exterior** to the planet

$$V_p \sim \frac{GM_p}{r^3} R_p^2 P_2(\cos \psi) \times \frac{h}{R_p}$$

$$V_p \sim \frac{Gm_s}{a} \left( \frac{R_p}{a} \right)^5 P_2(\cos \psi) = k_2 \frac{Gm_s}{a} \left( \frac{R_p}{a} \right)^5 P_2(\cos \psi)$$

Love number  $k_2$



Details about planet's response to the tidal field is incorporated into the unitless Love number

# Love numbers

Surface deformation  $\frac{h}{R} = h_2 \frac{V_T(R)}{g}$

Potential perturbation  $V_2(r, \theta) = -k_2 V_T(R) \left(\frac{R}{r}\right)^3 P_2(\cos \theta)$

$h_2, k_2$  are Love numbers

They take into account structure and strength of body

For uniform density bodies  $h_2 = \frac{5/2}{1 + \tilde{\mu}} \quad k_2 = \frac{3}{5} h_2$

$$\tilde{\mu} \equiv \frac{19\mu}{2\rho g R}$$

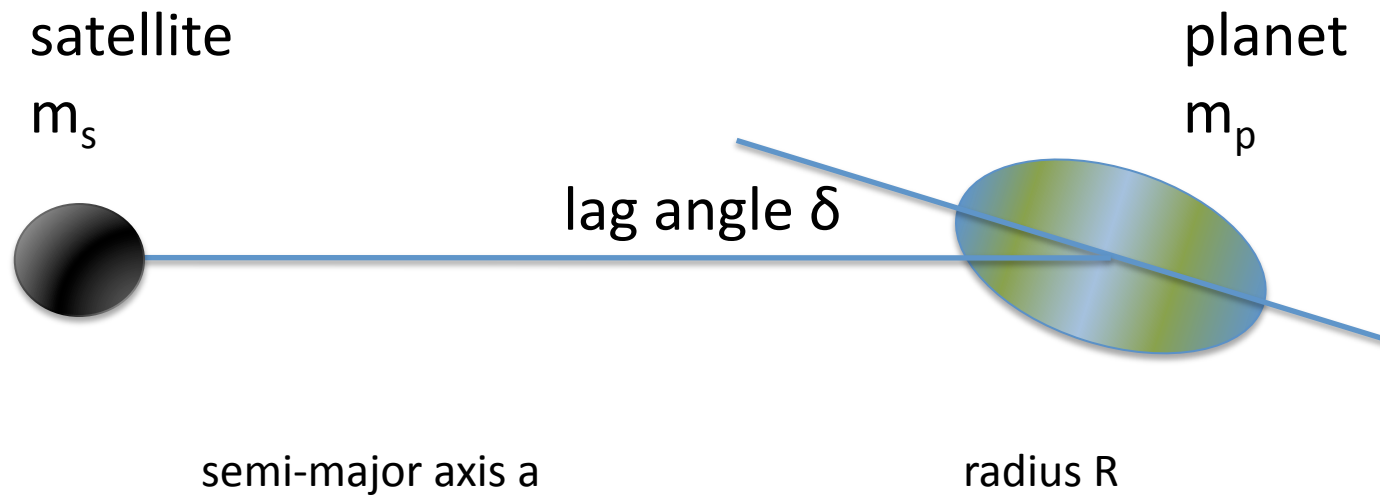
dimensional quantity  
ratio of elastic and  
gravitational forces at  
surface

$\mu$  is rigidity

# Love numbers

- $h_2 = 5/2$ ,  $k_2 = 3/2$  for a uniform density fluid
- These values sometimes called the equilibrium tide values. Actual tides can be larger- not in equilibrium (sloshing)
- For stiff bodies  $h_2, k_2$  are inversely proportional to the rigidity  $\mu$  and Love numbers are smaller
- Constraints can be made on the stiffness of the center of the Earth based on tidal response

# Tidal torque



# Tidal Torques

- Dissipation function  $Q = E/dE$ , energy divided by energy lost per cycle;  $Q$  is unitless
- For a driven damped harmonic oscillator the phase shift between response and driving frequency is related to  $Q$ :  $\sin \delta = -1/Q$
- Torque on a satellite depends on difference in angle between satellite planet line and deformation angle of satellite  $\Gamma = -m_s \frac{\partial \Phi}{\partial \psi}$   
and this is related to energy dissipation rate  $Q$



# Tidal Torques

- Torque on satellite is opposite to that on planet
- However rates of energy change are not the same (energy lost due to dissipation)
- Energy change for rotation is  $\Gamma\Omega$  (where  $\Omega$  is rotation rate and  $\Gamma$  is torque)
- Energy change on orbit is  $\Gamma n$  where  $n$  is mean motion of orbit.
- Angular momentum is fixed ( $dL/dt = 0$ ) so we can relate change of spin to change of mean motion

$$L = I\Omega + \frac{m_p m_s}{m_p + m_s} a^2 n \qquad \dot{\Omega} = -\frac{1}{2I} \frac{m_p m_s}{m_p + m_s} n a \dot{a}$$

# Tidal Torques

$$E = \frac{1}{2} I \Omega^2 - \frac{G m_p m_s}{2a}$$

$$\dot{E} = I \Omega \dot{\Omega} + \frac{1}{2} \frac{m_p m_s}{m_p + m_s} n^2 a \dot{a}$$

- Subbing in for  $d\Omega/dt$   $\dot{E} = \frac{1}{2} \frac{m_p m_s}{m_p + m_s} n a \dot{a} (\Omega - n)$
- As  $dE/dt$  is always negative the sign of  $(\Omega - n)$  sets the sign of  $da/dt$
- If satellite is outside synchronous orbit it moves outwards away from planet (e.g. the Moon) otherwise moves inwards (Phobos)

# Orbital decay and spin down

- Derivative of potential w.r.t  $\psi$  depends on

$$\frac{\partial P_2(\cos \psi)}{\partial \psi} = -\frac{3}{2} \sin 2\psi \quad C_p = R_p$$

- Torque depends on this derivative, the angle itself depends on the dissipation rate Q

$$\dot{a} = \text{sign}(\Omega_p - n) \frac{3k_2 m_s}{Q_p m_p} \left( \frac{C_p}{a} \right)^5 na$$

- where  $k_2$  is a Love number used to incorporate unknowns about internal structure of planet

- Computing the spin down rate ( $\alpha_p$  describes moment of inertia of planet  $I = \alpha_p m_p R_p^2$ )

$$\dot{\Omega}_p = -\text{sign}(\Omega_p - n) \frac{3k_2}{2\alpha_p Q_p} \frac{m_s^2}{m_p(m_p + m_s)} \left( \frac{C_p}{a} \right)^3 n^2$$

# Orbital decay

$$\dot{a} = \text{sign}(\Omega_p - n) \frac{3k_2}{Q_p} \frac{m_s}{m_p} \left( \frac{C_p}{a} \right)^5 na$$

- Tidal timescales for decay tend to be strongly dependent on distance.
- Quadrupolar force drops quickly with radius.
- Strong power of radius is also true for gravitational wave decay timescale

# Mignard A parameter

Satellite tide on planet

Planet tide on satellite

How to estimate which one is more important if both are rotating?

$$A \equiv \left( \frac{m_p}{m_s} \right)^2 \left( \frac{R_s}{R_p} \right)^5 \frac{k_{2s} Q_p}{k_{2p} Q_s}$$

A way to judge importance of tides dissipated in planet vs those dissipated in satellite

Spin down leads to synchronous rotation

When both bodies are tidally locked tidal dissipation ceases

# Eccentricity damping or Tidal circularization

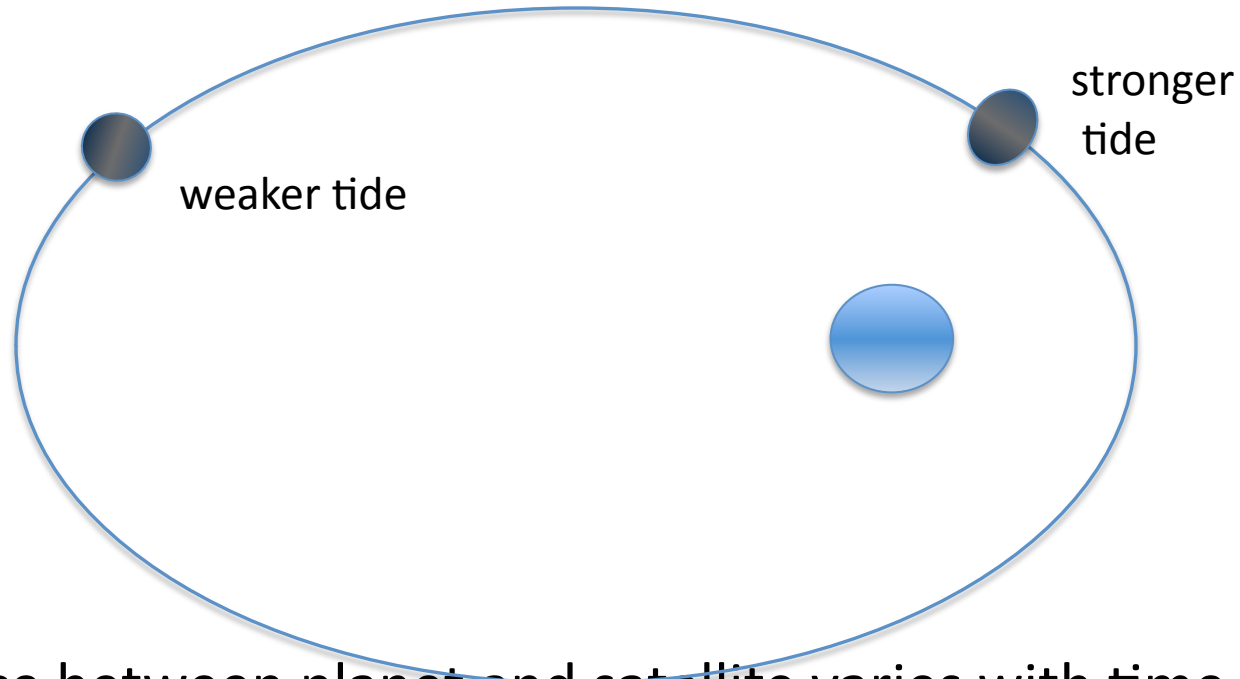
Neglect spin angular momentum, only consider orbital angular momentum that is now conserved

$$e^2 = 1 + \frac{2EL_{orb}^2}{G^2} \frac{(m_p + m_s)}{(m_p m_s)^3} \quad \dot{e} = -\frac{\dot{E}}{2eE} (1 - e^2) \approx -\frac{\dot{E}}{2eE}$$

- As  $dE/dt$  must be negative then so must  $de/dt$   
→ Eccentricity is damped
- This relation depends on  $(dE/dt)/E$  so is directly dependent on  $Q$  as were our previously estimated tidal decay rates

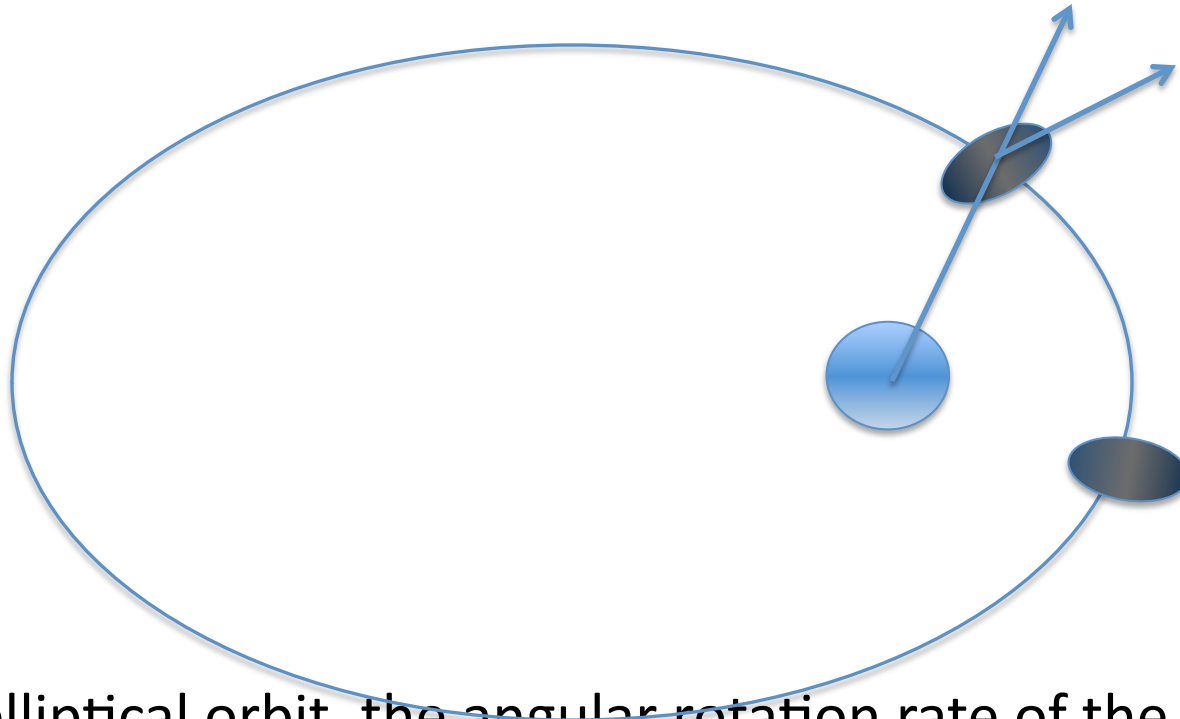
(Eccentricity can increase depending on Mignard A parameter).  
Moon's eccentricity is currently increasing.

# Tidal circularization (amplitude or radial tide)



- Distance between planet and satellite varies with time
- Tidal force on satellite varies with time
- Amplitude variation of body response has a lag → energy dissipation

# Tidal circularization (libration tide)



- In an elliptical orbit, the angular rotation rate of the satellite is not constant. With synchronous rotation there are variations in the tilt angle w.r.t to the vector between the bodies
- Lag  $\rightarrow$  energy dissipation



# Tidal circularization

Consider the gravitational potential on the surface of the satellite as a function of time

The time variable components of the potential from the planet due to planet to first order in  $e$

$$V_s = -\frac{Gm_p C_s^2}{a^3} [3e \cos nt P_2(\cos \beta) + 3e \sin^2 \theta \sin 2\phi \sin nt]$$

radial tide

libration tide

$\beta$  angle between position point in satellite and the line joining the satellite and guiding center of orbit

$\theta$  azimuthal angle from point in satellite to satellite/planet plane  
 $\phi$  azimuthal angle in satellite/planet plane

# Response of satellite

For a stiff body: The satellite response depends on the surface acceleration, can be described in terms of a rigidity in units of  $g$   
 $Vt \sim \mu g h$

$$h \sim \frac{m_p C_s^4}{a^3} \frac{e}{\tilde{\mu}}$$

Total energy is force x distance (actually stress x strain integrated over the body)

$$F \sim \frac{G m_p C_s}{a^3} e m_s$$

$$W \sim F h \sim \frac{G m_p^2}{a} \left( \frac{C_s}{a} \right)^5 \frac{e^2}{\tilde{\mu}}$$

This is energy involved in tide

Using this energy and dissipation factor  $Q$  we can estimate  $de/dt$

$$\frac{\dot{E}}{E} \sim \frac{n}{Q_s}$$

# Eccentricity damping or Tidal circularization

- Eccentricity decay rate for a stiff satellite

$$\tau_e = \frac{4}{63} \frac{m_s}{m_p} \left( \frac{a}{C_s} \right)^5 \frac{\mu_s Q_s}{n}$$

- where  $\mu$  is a rigidity. Sum of libration and radial tides.
- A high power of radius.
- Similar timescale for fluid bodies but replace rigidity with the Love number. Decay timescale rapidly become long for extra solar planets outside 0.1AU

# Tidal forces and resonance

- If tidal evolution of two bodies causes orbits to approach, then capture into resonance is possible
- Once captured into resonance, eccentricities can increase
- Hamiltonian is time variable, however in the adiabatic limit volume in phase space is conserved.
- Assuming captured into a fixed point in Hamiltonian, the system will remain near a fixed point as the system drifts. This causes the eccentricity to increase
- Tidal forces also damp eccentricity
- Either the system eventually falls out of resonance or reaches a steady state where eccentricity damping via tide is balanced with the increase due to the resonance

# Time delay vs phase delay

Prescriptions for tidal evolution

- Darwin-Mignard tides: constant time delay
- Darwin-Kaula-Goldreich: constant phase delay

phase angle  $\delta \sim \frac{1}{Q}$

spinning object  $\delta = (\Omega - n)\Delta t$

synchronously locked  $\delta = n\Delta t$

If  $\Delta t$  is fixed, then phase angle and  $Q$  (dissipation) changes with  $n$  (frequency)  
Lunar studies suggest that dissipation is a function of frequency (Efroimsky & Williams, recent review)

Tidal evolution taking into account normal modes: see Jennifer A. Meyer's recent work

# Tides expanded in eccentricity

For two rotating bodies, as a function of both obliquities and tides on both bodies

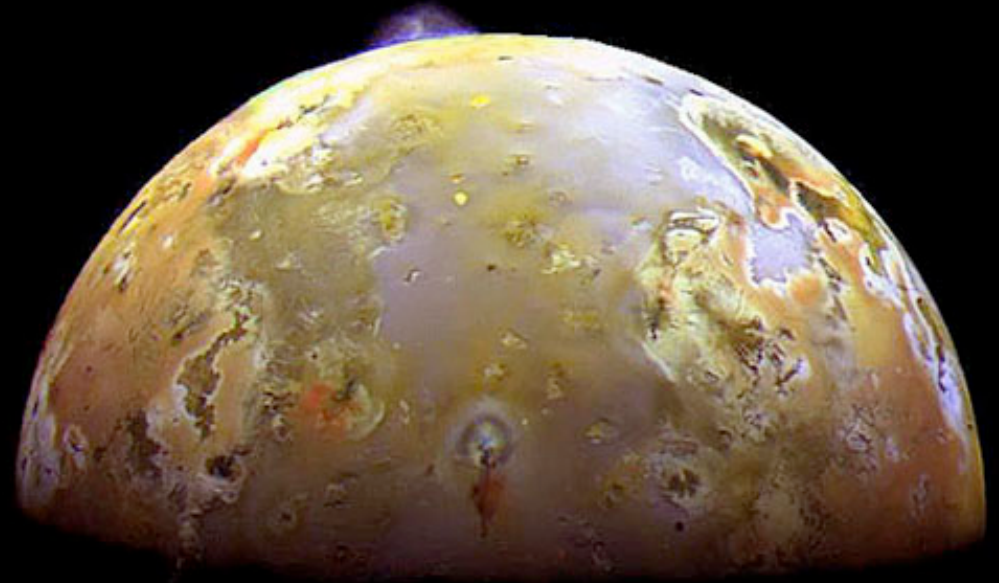
The Mignard evolutionary equations are:

$$\begin{aligned} \frac{dX}{dt} &= \frac{C_X}{X^7} \left[ -\frac{f_0}{\beta^{15}} (1+A) + \left( UX^{3/2} \cos i + A \frac{\omega'}{n} \cos(I') \right) \frac{f_1}{\beta^{12}} \right] \\ \frac{de}{dt} &= \frac{C_e}{X^8} \left[ -\frac{f_3}{\beta^{13}} (1+A) + \left( UX^{3/2} \cos i + A \frac{\omega'}{n} \cos(I') \right) \frac{f_4}{\beta^{10}} \right] \\ \frac{di}{dt} &= -\frac{C_i}{X^{13/2}} \sin i \left( U + \frac{A}{X^{3/2}} \right) \frac{f_2}{\beta^{10}} \\ \frac{dU}{dt} &= -C_{U,0} \left[ U - \frac{n_\odot}{n_G} \right] + C_{U,1} \frac{1}{X^{15/2}} \left[ \frac{f_1}{\beta^{12}} - UX^{3/2} \cos i \frac{f_2}{\beta^9} \right] \cos i \\ &\quad - C_{U,2} U (\sin i)^2 \frac{1}{X^6} \frac{f_2}{\beta^9} \\ \frac{d(\omega/n_G)}{dt} &= \frac{C_{\omega,0}}{X^6} \left[ -\frac{f_2}{\beta^9} \left[ \left( \frac{\omega}{n_G} \right)^2 \frac{2 + (\sin i)^2}{2} + U^2 \frac{3(\cos i)^2 - 1}{2} \right] \right. \\ &\quad \left. + 2U \cos i \frac{f_1}{\beta^{12}} \frac{1}{X^{3/2}} \right] + C_{\omega,1} \left[ 2 \frac{n_\odot}{n_G} U - \left( \frac{\omega}{n_G} \right)^2 - U^2 \right] \end{aligned}$$

where  $\beta = \sqrt{1 - e^2}$ ,  $U = (\omega/n_G) \cos(I)$ , the grazing mean motion  $n_G = \sqrt{GM/R_E^3}$ ,  $G$  is Newton's constant,  $X = a/R_E$ , with  $R_E$  the radius of the Earth,  $a$  is the semimajor axis of the lunar orbit,  $e$  the orbital eccentricity,  $n$  is the orbital mean motion,  $i$  is the orbital inclination to the ecliptic,  $I$  is obliquity,  $\omega$  is rotation rate,  $m$  is the mass of the Moon,  $M$  is the mass of the Earth,  $\mu = (1/m + 1/M)^{-1}$  is the reduced

# Tidal heating of Io

Peale et al. 1979 estimated that if  $Q_s \sim 100$  as is estimated for other satellites that the tidal heating rate of Io implied that its interior could be molten. This could weaken the rigidity and so lead to a runaway melting events. Io could be the most “intensely heated terrestrial body” in the solar system



Morabita et al. 1979 showed Voyager I images of Io displaying prominent volcanic plumes. Voyager I observed 9 volcanic eruptions. Above is a Galileo image

# Tidal evolution

- The Moon is moving away from Earth.
- The Moon/Earth system may have crossed or passed resonances leading to heating of the Moon, its current inclination and affected its eccentricity (Touma et al.)
- Satellite systems may lock in orbital resonances
- Estimating  $Q$  is a notoriously difficult problem as currents and shallow seas may be important
- $Q$  may not be geologically constant for terrestrial bodies (in fact: can't be for Earth/moon system)
- Evolution of satellite systems could give constraints on  $Q$  (work backwards)



# Consequences of tidal evolution

- Inner body experiences stronger tides usually
- More massive body experiences stronger tidal evolution
- Convergent tidal evolution (Io nearer and more massive than Europa)
- Inner body can be pulled out of resonance w. eccentricity damping (Papaloizou, Lithwick & Wu, Batygin & Morbidelli) possibly accounting for Kepler systems just out of resonance

# Static vs Dynamic tides

- We have up to this time considered very slow tidal effects
- Internal energy of a body  $Gm^2/R$
- Grazing rotation speed is of order the low quantum number internal mode frequencies  $(Gm/R^3)^{1/2}$
- During close approaches, internal oscillation modes can be excited
- Energy and angular momentum transfer during a pericenter passage depends on coupling to these modes (e.g. Press & Teukolsky 1997)
- Tidal evolution of eccentric planets or binary stars
- Tidal capture of two stars on hyperbolic orbits

# Energy Deposition during an encounter

following Press &  
Teukolsky 1977

$$\dot{E} = \int dV \rho \mathbf{v} \cdot \nabla \Phi$$

dissipation rate depends on  
motions in the perturbed body

$$\Phi(\mathbf{r}, t) = \frac{GM}{|\mathbf{r} - \mathbf{R}(t)|}$$

perturbation potential

$$\mathbf{v} = \frac{\partial \xi}{\partial t}$$

velocity w.r.t to  
Lagrangian fluid motions

$$\Delta E = \int dt \dot{E}$$

total energy exchange

Describe both potential and displacements in terms of  
Fourier components

Describe displacements in terms of a sum of normal modes  
Because normal modes are orthogonal the integral can  
be done in terms of a sum over normal modes

# Energy Deposition due to a close encounter

Potential perturbation described in terms of a sum over normal modes

$$\nabla\Phi = \sum A_n(\omega)\xi_n$$

$$\Delta E \propto \sum |A(\omega)|^2$$

energy dissipated depends on “overlap” integrals of tidal perturbation with normal modes

dimensionless expression

$$\eta \equiv \sqrt{\frac{M_*}{M_* + m}} \sqrt{\frac{d^3}{R_*^3}} \quad \text{d=pericenter}$$

internal binding  
energy of star

strong dependence on distance of pericenter to star

$$\delta E = \left(\frac{GM_*^2}{R_*}\right) \left(\frac{m}{M_*}\right)^2 \sum_l \left(\frac{R_*}{d}\right)^{2l+2} T_l(\eta) \quad \text{multipole expansion}$$

to estimate dissipation and torque, you need to sum over modes of the star/planet, often only a few modes are important

# Capture and circularization

- Previous assumed no relative rotation. This can be taken into account (e.g., Invanov & Papaloizou 04, 07 ...)
- “quasi-synchronous state” that where rotation of body is equivalent to angular rotation rate a pericenter
- Excited modes may not be damped before next pericenter passage leading to chaotic variations in eccentricity (work by R. Mardling)

# Tidal predictions taking into account normal modes of a planet

- Recent work by Jennifer Meyer on this

# Hot Jupiters

- Critical radius for tidal circularization of order 0.1 AU
- Rapid drop in mean eccentricity with semi-major axis. Can be used to place a limit on  $Q$  and rigidity of these planets using the circularization timescale and ages of systems
- Large eccentricity distribution just exterior to this cutoff semi-major axis
- Large sizes of planets found via transit surveys a challenge to explain.

# Possible Explanations for large hot Jupiter radii

- They are young and still cooling off
- They completely lack cores?
- They are tidally heated via driving waves at core boundary rather than just surface (Ogilvie, Lin, Goodman, Lackner)
- Gravity waves transfer energy downwards
- Obliquity tides. Persistent misalignment of spin and orbital angular momentum due to precessional resonances (Cassini states) (A possibility for accounting for oceans on Europa?)
- Evaporation of He (Hanson & Barman) Strong fields limit loss of charged Hydrogen but allow loss of neutral He leading to a decrease in mean molecular weight
- Ohmic dissipation (e.g., Batygin)
- Kozai resonance (e.g., Naoz)



# Cooling and Day/Night temperatures

- Radiation cooling timescale sets temperature difference
- If thermal contrast too large then large winds are driven day to night (advection)
- Temperature contrast set by ratio of cooling to advection timescales (Heng)

# Quadrupole moment of non-round bodies

- For a body that is uneven or lopsided like the moon consider the ellipsoid of inertia (moment of inertial tensor diagonalized)
- Euler's equation, in frame of rotating body

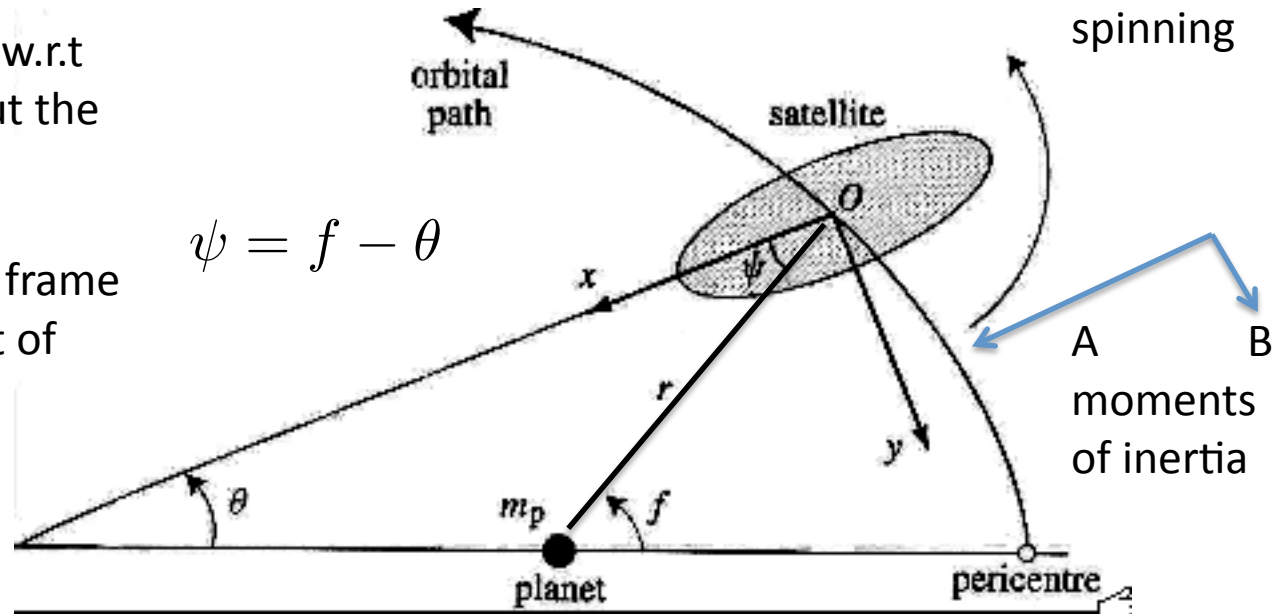
$$\Gamma = \dot{L} + \omega \times L = I\dot{\omega} + \omega \times L$$

- Set this torque to be equal to that exerted tidally from an exterior planet

# Spin orbit coupling

spin of satellite w.r.t  
to its orbit about the  
planet

Fixed reference frame  
taken to be that of  
the satellite's  
pericenter



$$\psi = f - \theta$$

- A,B,C are from moment of inertia tensor
- Introduce a new angle related to mean anomaly of planet
- A resonant angle

$$C\ddot{\theta} - \frac{3}{2}(B - A)\frac{Gm_p}{r^3} \sin 2\psi = 0$$

$$\gamma = \theta - pM \quad p = i/j$$

$$\ddot{\gamma} = \ddot{\theta} \quad p \text{ is integer ratio}$$

# Spin orbit resonance

$$\ddot{\gamma} + \frac{3}{2}n^2 \left( \frac{B - A}{C} \right) \left( \frac{a}{r} \right)^3 \sin(2\gamma + 2pM - 2f)$$

- Now can be expanded in terms of eccentricity  $e$  of orbit using standard expansions
- If near a resonance then the angle  $\gamma$  is slowly varying and one can average over other angles
- Finding an equation that is that of a pendulum

$$\ddot{\gamma} \sim -\frac{\omega_0^2}{2} \sin 2\gamma$$

# Spin Orbit Resonance

- Libration Frequency

$$\omega_0 = n \left[ 3 \left( \frac{B-A}{C} \right) H(p, e) \right]^{0.5}$$

$A = \sum \delta m (y^2 + z^2)$	$H(-1, e) = \frac{1}{24} e^4$	$H(-\frac{1}{2}, e) = \frac{1}{48} e^4$	$H(0, e) = 0$
$B = \sum \delta m (x^2 + z^2)$	$H(\frac{1}{2}, e) = -\frac{1}{2} e + \frac{1}{16} e^3$	$H(1, e) = 1 - \frac{5}{2} e^2 + \frac{1}{16} e^4$	$H(\frac{3}{2}, e) = \frac{7}{2} e - \frac{123}{16} e^3$
$C = \sum \delta m (x^2 + y^2)$	$H(\frac{5}{2}, e) = \frac{845}{48} e^3$	$H(3, e) = \frac{533}{16} e^4$	



# Spin Orbit Resonance and Dynamics

- Tidal force can be expanded in Fourier components
- Contains high frequencies if orbit is not circular
- Eccentric orbit leads to oscillations in tidal force which can trap a spinning non-spherical body in resonance
- If body is sufficiently lopsided then motion can be chaotic

# Reading

- M+D Chap 4, 5